

MANUAL AND MAINTENANCE GUIDELINES



**PNEUMATIC ACTUATOR** 

PRD/PRE

Documentnr.: BWA.PRD.201201 | Issue: Dec. 2020

# Manual and maintanance Guidelines Pneumatic actuator Type PRD/PRE

### **Contents:**

Chapter 1:	Prep	aration				
	1.1	Marking of reference	Page 4			
	1.2	Safety fundamentals	Page 4			
	1.3	Transport, storage and packaging	Page 4			
Chapter 2:	Preliminary					
	2.1	Description	Page 5			
	2.2					
	2.3	Technical data	Page 6			
	2.4	Type code	Page 6			
Chapter 3:	Function					
	3.1	Fundamentals	Page 7			
	3.2	Mounting versions	Page 8			
Chapter 4:	Installation					
	4.1	Attachment to a valve	Page 10			
	4.2	Pneumatic connection	Page 11			
	4.3	End stop adjustment	Page 12			
Chapter 5:	Maintenance					
	5.1	General	Page 14			
	5.2	Safety instructions	Page 14			
	5.3	Tightening torques for screw connections	Page 14			
	5.4	Components	Page 14			
	5.5	Arrangement of safety springs	Раде 15			

### Copyright

This document is protected by copyright. We reserve all rights to this manual before proceeding, even the reproduction and / or duplication in any thinkable form, e.g. photocopying, printing, on data medium or in translated form. Reproduction of this manual only with written permission of ProtACT GmbH. The technical state at the time of delivery of device and manual is decisive, if no other information is given. We reserve the right to make technical modifications without specific notice. Earlier instructions then become invalid.

### **Chapter 1: Preparation**

Content:

- Marking of safety instructions
- Safety fundamentals
- Instructions for storage

### 1.1 Marking of safety instructions



This symbol indicates safety instructions which can cause personal injury if not respected.



This symbol indicates an important note

### 1.2 Safety fundamentals



Failure to follow the safety basics can void the warranty claims.



Rotary actuators must be isolated both pneumatically and electrically before any intervention.

The installation, assembly, commissioning, maintenance and any other work on pneumatic actuators must be performed by qualified personnel.

This manual is part of the device and must be available for the operating personnel at all times. This manual must be read and understood before operation.

The device may only be operated in perfect condition. No safety devices are removed or deactivated. A rebuilding or modification of the device is strictly prohibited.



Installation, operation and maintenance of the products are strictly subject to the local safety and accident prevention regulations!

### 1.3 Transport, storage and packaging

The devices must be carefully handled, transported and stored.

The devices should be transported to the end destination in their original packaging and unpacked immediately before installation.

The actuators are to be stored in a clean, dry storage, which is neither exposed to excessive vibration nor to rapid temperature changes.

Prevent ingress of dirt or moisture into the actuator. Close or tighten both air connections.

Proper disposal of packaging is the customer's responsibility.



Failure to comply may void the warranty claims.

### **Chapter 2: Preliminary**

#### Content:

- Design description
- Intended use
- Technical information
- Type code

### 2.1 Description

Actuators of the PRD/PRE series are pneumatic double-piston rotary actuators. They are generally used in two different modes: single acting and double-acting.

Double piston principle means that two pistons create two pressure chambers. By inflating one of these chambers the pistons are moved into opposite directions either towards or away from each other. The resulting force is provided to the central actuator pinion via toothed racks which are connected with the pistons and so creates a constant torque over the entire pivoting angle.

The actuator series PRD/PRE offers 18 sizes with a torque range of 3-15880 Nm. Standardized interfaces for mounting accessories (VDI / VDE3845, NAMUR, ISO5211, DIN3337) are available.

In the single acting type integrated springs ensure the closing or opening in the event of a failure of the control medium ("spring to close" or "spring to open").

#### 2.2 Intended use

Actuators of the PRD/PRE series are primarily used for the automation of quarter-turn valves such as ball valves, butterfly valves or plug valves, but can also be used for other applications. Contact our qualified personnel where required.

The specified operating and limiting values for temperature, pressure, control medium, etc. must be observed.

In operation of valves high kinetic energies may arise, which are transmitted to the actuator. Make sure that the drive is protected from damage by complying with the minimum travel times safely. Control speed can be reduced by the use of choke valves, which can be purchased through our sales department.

For valve types with high flywheel mass and low torque requirements the operating conditions of the drive must be coordinated with us in advance.

The actuator may only be used:

- in perfect condition
- as stipulated
- safety- and danger-conscious in consideration of the operating instructions
- if all safety devices are in place and functioning

In particular faults which may affect safety are to be eliminated!



Any use not pre-approved by the manufacturer is considered improper!

#### 2.3 Technical Data

**Construction principle** Pneumatic double-piston rotary actuator in rack&pinion-design with self-centering

pistons; double- and single-acting execution

Temperature range Standard: -50°C to +70°C (NBR)

Lowtemperature:  $-15^{\circ}\text{C to } +160^{\circ}\text{C (Viton)}$ Hightemperature:  $-60^{\circ}\text{C to } +80^{\circ}\text{C (Silikon)}$ 

Control pressure 2 to 8 bar

**Pressure media** dry, filtered air or inert gases in respect of remaining oil-, dust and water-content

according to DIN ISO 8573-1 / class 4, maximum particle diameter 30μm, dew point

minimum 10°C below ambient temperature

Nominal rotation angle 90°,120°, 180° resp. 240°

Adjustable in one end position +/-5° (optional 100% stroke adjustment)

Version BE: Adjustable in both end positions

**Torque range** to 6.400 Nm (double-acting)

to 4.157 Nm (single-acting)

Standards ISO 5211, VDI/VDE 3845 resp. NAMUR

Materials Housing: Anodised aluminum ASTM 6083, UNI 4522

Cap: Aluminum UNI 5076, epoxy resin coated

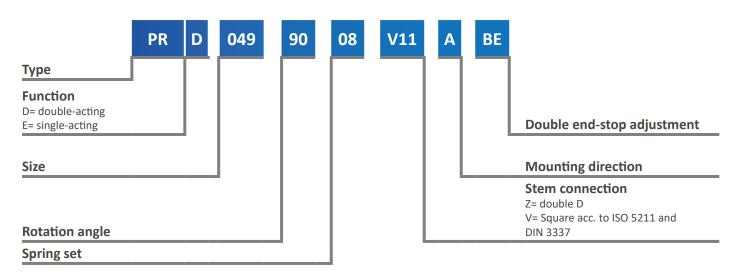
Piston: Aluminum UNI 5076

Pinion: Steel, nickel-plated (optional: stainless steel)

Bearings: POM

Sealings: NBR, optional: FKM or silicone

### 2.4 Type code



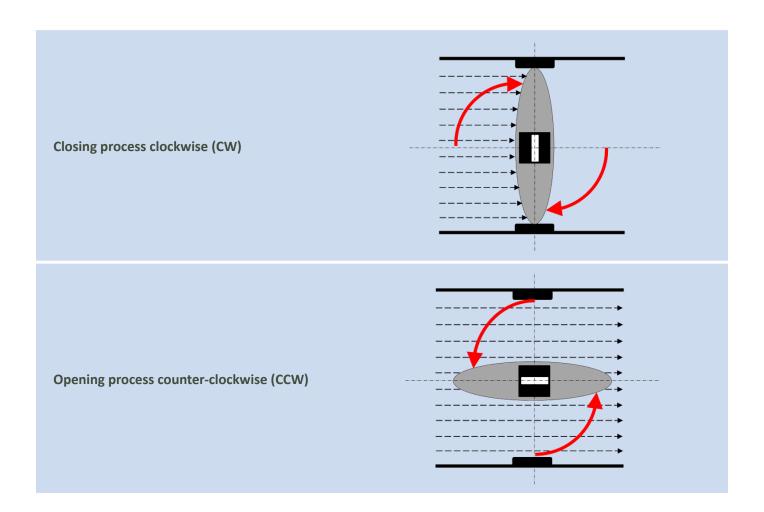
### **Chapter 3: Function**

#### Content:

- Fundamentals
- Mounting versions (mounting direction/spring rotation sense)

### 3.1 Fundamentals

General rule is that valves are closed clockwise (CW) and opened counterclockwise (CCW). The angle of view is to be understood as "from the top onto the valve shaft." All statements in this manual are based on this rule and have to be taken into account accordingly



### 3.2 Mounting versions

Depending on the orientation of the actuator to the pipeline (parallel or transverse) and the switching function (clockwise or counterclockwise), there are 4 resulting mounting versions which need to be differentiated.

## **Mounting version F** Actuator parallel to pipeline Spring rotation sense clockwise (CW) **SPRING TO CLOSE** Port "A" pressurized, actuator moves in Port "B" pressurized, actuator moves in switched position 90°, valve opens inital position 0°, valve closes double-acting Valve position single-acting Port "A" pressurized, actuator moves in Port "A" vented, actuator moves in inital switched position 90°, valve opens position 0°, valve closes **Mounting version H Actuator parallel to pipeline** Spring rotation sense counter-clockwise (CCW) **SPRING TO OPEN** Port "A" pressurized, actuator moves in Port "B" pressurized, actuator moves in switched position 90°, valve closes inital position 0°, valve opens double-acting Valve position single-acting Port "A" pressurized, actuator moves in Port "A" vented, actuator moves in inital

switched position 90°, valve closes

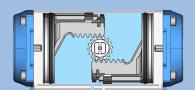
position 0°, valve opens

### **Mounting version E**

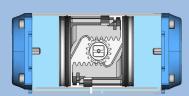
Actuator transversal to pipeline
Spring rotation sense clockwise (CW)
SPRING TO CLOSE

double-acting

Port "A" pressurized, actuator moves in switched position 90°, valve opens



Port "B" pressurized, actuator moves in inital position 0°, valve closes

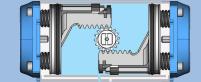


Valve position

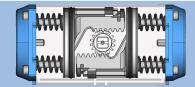


5

single-acting



Port "A" pressurized, actuator moves in switched position 90°, valve opens



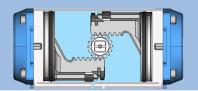
Port "A" vented, actuator moves in inital position 0°, valve closes

### **Mounting version G**

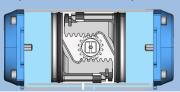
Actuator transversal to pipeline
Spring rotation sense counter-clockwise (CCW)
SPRING TO OPEN

double-acting

Port "A" pressurized, actuator moves in switched position 90°, valve closes



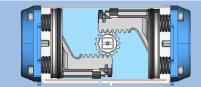
Port "B" pressurized, actuator moves in inital position 0°, valve opens



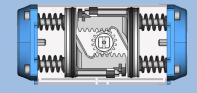
Valve position



single-acting



Port "A" pressurized, actuator moves in switched position 90°, valve closes



Port "A" vented, actuator moves in inital position 0°, valve opens

### **Chapter 4: Installation**

#### Content:

- Attachment to a valve
- Pneumatic connection
- End stop and stroke adjustment

#### 4.1 Attachment to a valve

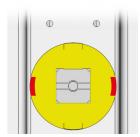


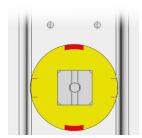
Perform any kind of installation work on rotary actuators exclusively when the device is fully vented!



Verify that the maximum actuator torque is below the maximum valve torque (MAST) to avoid further damage.

- During the installation of the actuator the tap hole (with ball and plug valves) respectively the disc (butterfly valves) must correspond with the groove at the top of the drive pinion in order to ensure the proper function of further adapted signal- or control units. The groove (according to VDI / VDE 3845) symbolically represents the valve position.
- After correct installation of the actuator to the valve ensure that the visual position indicator is also programmed correctly by adjusting the signal plates.
   These must correspond to the pinion groove and thus with the valve position.





- Make sure that the valve shaft corresponds to the terminal in the actuator pinion in terms of shape and dimension. For direct mounting possible differences can usually be compensated by the use of reduction inserts. These can be ordered via our sales department separately.
- Check whether valve and actuator have a corresponding adaption interface. If not, an additional mounting kit is required, which can be ordered via our sales department.
- Secure the drive with screws on the valve. We recommend using stainless steel screws to ensure a corresponding corrosion resistance. The number of screws is relevant for the stability of the mounting and power transmission. Therefore, don't leave any fixation point unused. Take into account the tightening torques in section 5.3 when fixing the screws.

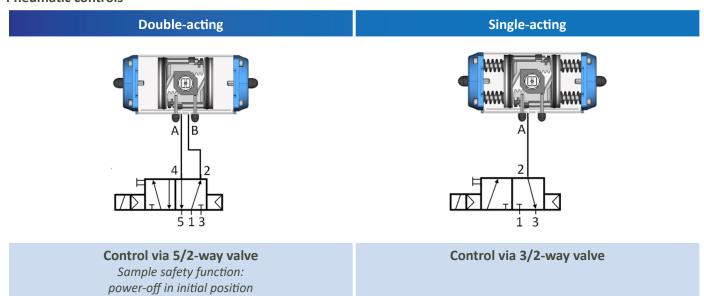
#### 4.2 Pneumatic connection

Actuators of the PRD/PRE series can either be controlled via a rigid or flexible tube system, with the control valve mounted apart from the actuator, or by a control valve that is directly mounted to the NAMUR interface according to VDI/VDE3845 in the body of the actuator.

By the design and mounting direction of the control valve security functions for the event of a power failure can be preset in double acting applications. For spring return actuators, the initial position is in principle understood as a safety position in case of power failure or failure of the control media.

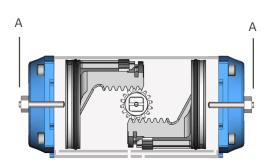
Single-acting actuators are factory wise equipped with a silencer in port "B". Prior to any installation of a directly mounted control valve that silencer is to be removed.

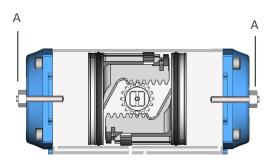
#### Pneumatic controls

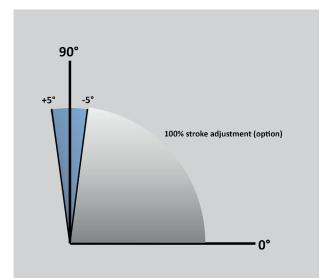


### 4.3 End stop adjustment

### Version "Standard"

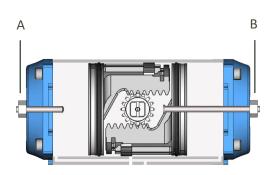


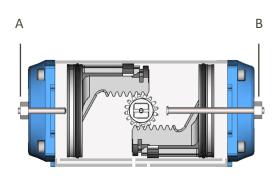


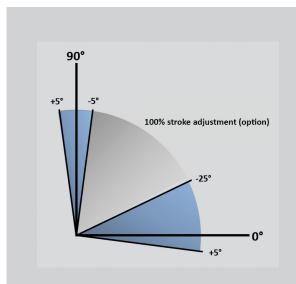


By turning the end-stop adjustment screws "A" , both end positions can be adjusted by  $\pm$ -5° for a precise setting of the final valve position. The according settings are secured by tightening the lock nuts.

### Version "BE"







With the optional version "BE" both end positions can be independently adjusted by turning the adjustment screws "A" and "B".

### 5. Maintenance

#### Content:

- General
- Safety instructions
- Tightening torques for screw connections
- Actuator components and spare parts
- Dismounting from a valve
- Disassembly / assembly of an actuator

#### 5.1 General

Actuators of the PRD/PRE series are designed for "no need of maintenance" during the normal lifecycle and are supplied with sufficient lubrication for their normal span of duty. The normal span of duty depends on the actuator size and is subject to EN 15714-3.

Perform periodic inspections to ensure trouble-free operation. Check whether visible or audible defects are present. Regular replacement of the seals and bearings in the actuator extend the normal span of duty. Appropriate spare parts kit can be ordered via our sales department.

### **5.2 Safety instructions**

Rotary actuators must be isolated both pneumatically and electrically before any work is performed.

Actuators and the connected valve can move when the control pressure and/or an electrical control signal is removed.



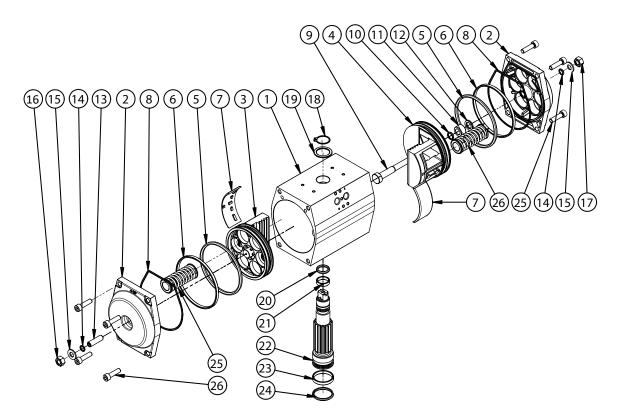
Single acting actuators with incomplete spring stroke contain a high spring force that can trigger a sudden rotation during dismounting of the actuator. This can cause serious injuries or property damage.

Work on electrical installations must be carried out exclusively by suitably qualified persons. A disabled supply must be protected against accidental reconnection.

### **5.3 Tightening torques for screw connections**

Tightening torques in Nm						
Nominal size	min.	max.				
M5	4,9	6				
M6	8	10				
M8	20	25				
M10	40	49				
M12	69	86				
M16	170	210				
M18	235	290				
M20	330	410				

### **5.4 Components**



No.	Description	Quantity	Spare parts set							
			Set 1	Set 2	Set 3	Set 4	Set 5	Set 6	Set 7	Set 8
1	Actuator body	1	-	-	-	-	-	-	-	-
2	Actuator end cap	2	1	-	-	-	-	-	-	-
3	Blind piston	1	-	1	-	-	-	-	-	-
4	Drilled piston	1	-	-	1	-	-	-	-	-
5	Piston sealing O-Ring	2	-	1	1	-	-	-	2	-
6	Piston guide ring	2	-	1	1	-	-	-	-	2
7	Piston guide skate	2	-	1	1	-	-	-	-	2
8	End cap sealing O-Ring	2	1	-	-	-	-	-	2	-
9	Internal travel stop rod	1	-	-	-	-	1	-	-	-
10	Internal travel stop rod sealing O-Ring	1	-	-	-	-	1	-	1	-
11	Internal stop rod guide bush	1	-	-	-	-	1	-	-	-
12	Rod guide bush stop washer	1	-	-	-	-	1	-	-	-
13	External travel stop screw	1	1	-	-	-	-	1	-	-
14	Stop sealing O-Ring	2	1	-	-	-	-	1	2	-
15	O-Ring stop washer	2	1	-	-	-	-	1	-	-
16	External stop nut	1	1	-	-	-	-	1	-	-
17	Internal stop nut (yellow)	1	-	-	-	-	1	-	-	-
18	Pinion stop circlips	1	-	-	-	1	-	-	-	-
19	Upper pinion washer	1	-	-	-	1	-	-	-	1
20	Upper pinion O-Ring sealing	1	-	-	-	1	-	-	1	-
21	Upper pinion guide ring	1	-	-	-	1	-	-	-	1
22	Pinion	1	-	-	-	1	-	-	-	-
23	Lower pinion guide ring	1	-	-	-	1	-	-	-	1
24	Lower pinion O-Ring sealing	1	-	-	-	1	-	-	-	-
25	End cap screws	8	4	-	-	-	-	-	-	-
26	Spring cartridges	0 - 12	-	-	-	_	-	-	-	-

Set 1 = Cap, complete

Set 2 = Blind piston, complete

Set 3 = Drilled piston kit, complete

Set 4 = Shaft complete

Set 5 =Internal stop kit, complete

Set 6 = External stop ki t, complete

Set 7 = Seal kit

Set 8 = Guide kit

### **5.5** Arrangement of safety springs



The drive pistons are not symmetrical due to the attached racks. In order to ensure optimal flow of force and minimize internal wear, the springs must be installed according to the following installation schemes.

Pay attention that in the following illustration the spring pocket, which is aligned with the piston, is highlighted with a point.

	Piston left/right		Piston left/right				
5 springs		6 springs					
7 springs		8 springs					
9 springs	00 00	10 springs	00 00				
11 springs	00 00	12 springs	00 00 00				

**ProtACT GmbH**Märkerstraße 18
56307 Dernbach

Tel: +49 (0) 2605 96 25 19-0 Fax: +49 (0) 2605 96 25 19-6 Email: protact@protact-gmbh.de

Website: www.protact-gmbh.de